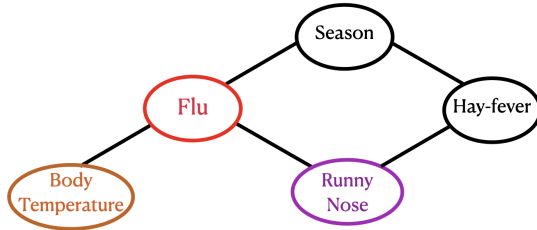


## Markov Random Fields

- Diagrammatic representations of probability distributions with a Markovian structure.



### Local Markov Property

- Given value of neighbors, a node is independent of the remaining nodes e.g., **Body Temperature**  $\perp\!\!\!\perp$  **Runny Nose** | **Flu**.

### Pairwise Markov Random Fields

- Consider an undirected graph  $G = ([p], E)$  where the nodes correspond to a  $p$ -dimensional random vector  $\mathbf{x}$ , and  $E$  denotes the edge set.
- Any strictly positive distribution in the family of pairwise MRF represented by  $G$  factorizes as :

$$f_{\mathbf{x}}(\mathbf{x}) \propto \exp\left(\sum_{i \in [p]} g_i(x_i) + \sum_{(i,j) \in E} g_{ij}(x_i, x_j)\right).$$

Examples	$g_i(x_i)$	$g_{ij}(x_i, x_j)$
Ising	$\theta^{(i)} x_i$	$\theta^{(ij)} x_i x_j$
Discrete	$\theta^{(i)}(x_i)$	$\theta^{(i)}(x_i)$
Gaussian	$\theta_1^{(i)} x_i + \theta_2^{(i)} x_i^2$	$\theta^{(ij)} x_i x_j$

- Limited progress for continuous (non-Gaussian) MRFs.**

### Learning Markov Random Fields

- Structure Recovery** : Given independent samples of  $\mathbf{x}$ , estimate the underlying graph structure.
- Parameter Recovery** : Given independent samples of  $\mathbf{x}$ , estimate all the associated parameters.

## Generalized Interaction Screening Objective

Vuffray, Misra, Lohov - NeurIPS 2020

- GISO is a node specific convex objective function.
- GISO can recover the graph structure and the ‘edge’ parameters (but not the ‘node’ parameters) in discrete graphical models with  $\Omega(\log p)$  samples.
- GISO is ingenious but unusual as it does not contain any partition function.
- If  $f_{x_i}(x_i | x_{-i} = x_{-i}; \theta) \propto \exp(g(\theta, \mathbf{x}))$ , then population GISO for node  $i$  is  $\mathbb{E}\left[\exp(-g(\theta, \mathbf{x}))\right]$ .

## Problem Formulation

### Continuous random variables

- Bounded Domain**: Random variables are bounded.
- Parametric potentials** :  $g_i(\cdot) = \theta^{(i)T} \phi(\cdot)$ , and  $g_{ij}(\cdot, \cdot) = \theta^{(ij)T} \psi(\cdot, \cdot)$ .
- Examples** : 1. Polynomial basis 2. Harmonic basis
- Bounded parameters** : Parameters are bounded.
- Sparsity** : Maximum degree of any node of the underlying graph is at-most  $d$ .

## Algorithm

### Step 1 - Learn graph structure and edge parameters

- For any  $i \in [p]$  the conditional density of  $x_i$  is :

$$f_{x_i}(x_i | x_{-i} = x_{-i}; \vartheta^{(i)}) \propto \exp\left(\vartheta^{(i)T} \varphi^{(i)}(\mathbf{x})\right).$$

where  $\vartheta^{(i)}$  consists of node parameters and edge parameters involving node  $i$  and  $\varphi^{(i)}(\cdot)$  is a function of the node and edge basis.

$$\text{Population GISO} = \mathbb{E}\left[\exp\left(-\vartheta^T \varphi^{(i)}(\mathbf{x})\right)\right].$$

- GISO be adapted to recover the graph structure and the ‘edge’ parameters in continuous graphical models!

## Algorithm

### Step 2 - Learn node parameters

- For any  $i \in [p]$  the conditional density of  $x_i$  is:  $f_{x_i}(x_i | x_{-i} = x_{-i}; \vartheta^{(i)}) \propto \exp\left(\lambda^T(x_{-i}) \phi(x_i)\right)$  where  $\lambda(x_{-i})$ , the canonical parameter, is linear function of node and edge parameters.
- By **duality of exponential family**, if we know  $\mu(x_{-i}) := \mathbb{E}[\phi(x_i) | X_{-i} = x_{-i}]$ , we can learn  $\lambda(x_{-i})$ .
- Learning  $\mu(x_{-i})$  is a **regression problem**.
- The regression function  $\mu(\cdot)$  is Lipschitz  $\rightarrow$  approximately **linearize**  $\mu(\cdot)$   $\rightarrow$  a **sparse linear regression problem**.

## Main Results

For discrete or continuous random variables

### 1 - Population GISO is equivalent to ‘local’ MLE

- $\arg \min \text{Population GISO} = \arg \min D(\cdot \| \cdot)$  where  $D(\cdot \| \cdot)$  is a node-specific KL divergence.

### 2 - GISO is asymptotically consistent and normal

- The traditional MLE is intractable.
- ‘Local’ M-estimation is tractable (but not asymptotically efficient).

For continuous random variables

### 3 - Structure recovery with $\Omega(\exp(d) \log p)$ samples

### 4 - Parameter recovery with $\Omega(\exp(d) \log p)$ samples

- All of the existing methods require some stringent conditions, for example - *incoherence*, *dependency*, *sparse eigenvalue* or *restricted strong convexity*.
- Our work does not require any of these conditions.**