

On Counterfactual Inference with Unobserved Confounding

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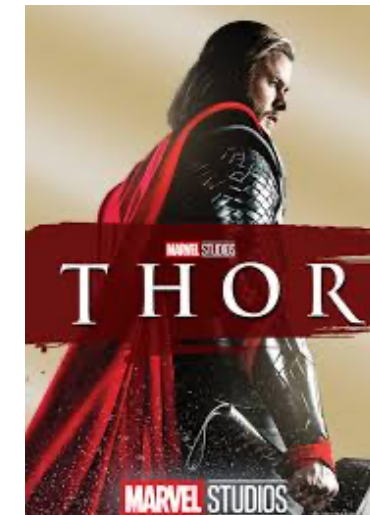


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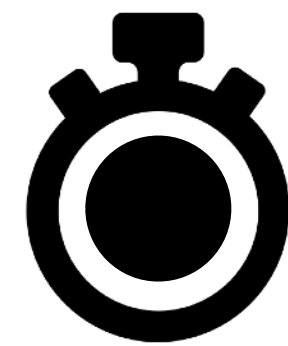
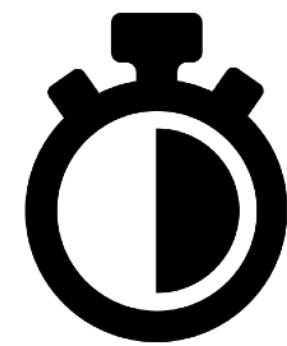


Greg Wornell
MIT

Observational Setting



a — action/intervention



y — outcome



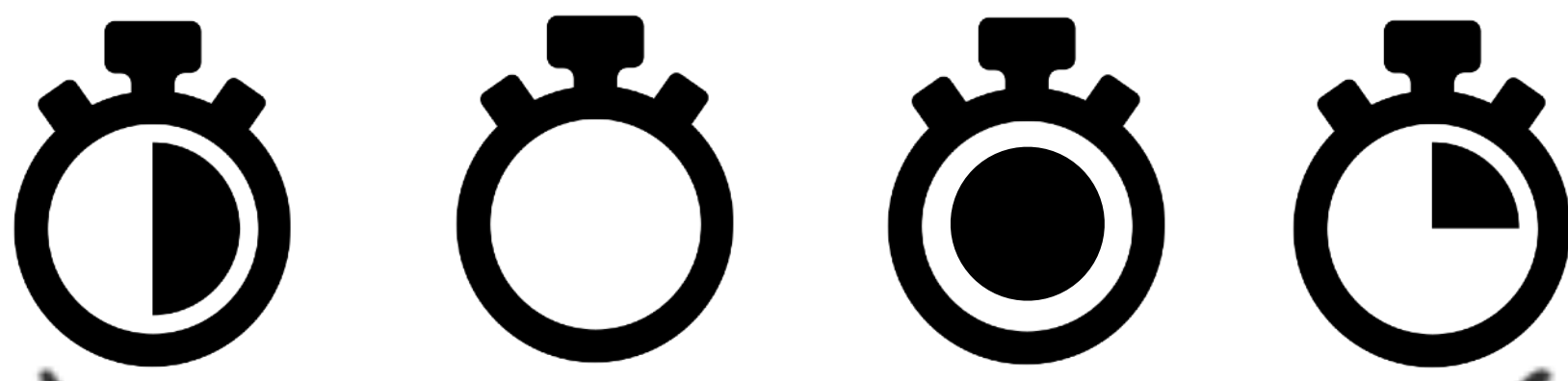
Panel Data







$\mathbf{a}^{(1)}$



$\mathbf{y}^{(1)}$

Potential Outcomes

$$\{\mathbf{y}^{(1)}(\mathbf{a})\}_{\mathbf{a} \in \mathcal{A}}$$

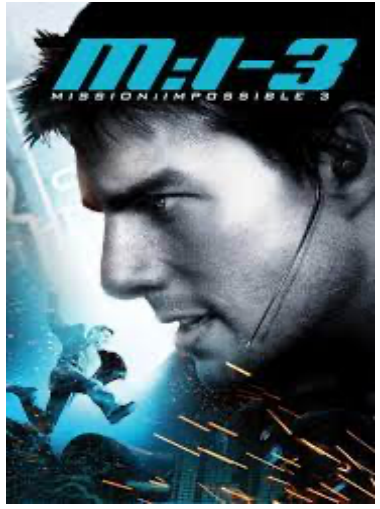
$$\mathbf{y}^{(1)} = \mathbf{y}^{(1)}(\mathbf{a}^{(1)})$$

⋮

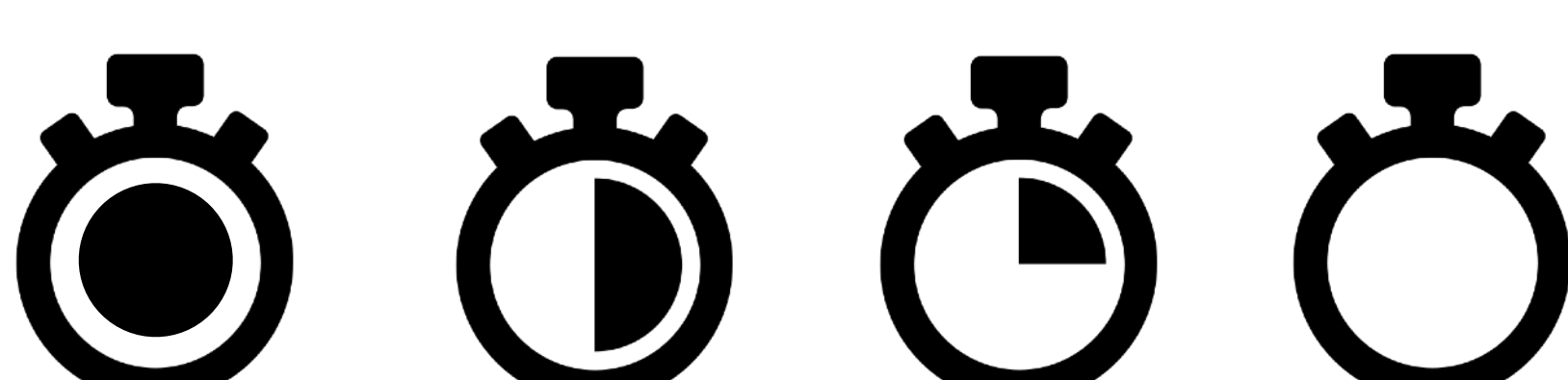
⋮

⋮




$\mathbf{a}^{(n)}$



$\mathbf{y}^{(n)}$

$$\{\mathbf{y}^{(n)}(\mathbf{a})\}_{\mathbf{a} \in \mathcal{A}}$$

$$\mathbf{y}^{(n)} = \mathbf{y}^{(n)}(\mathbf{a}^{(n)})$$

Goal: What-if?



$\tilde{\mathbf{a}}^{(1)}$

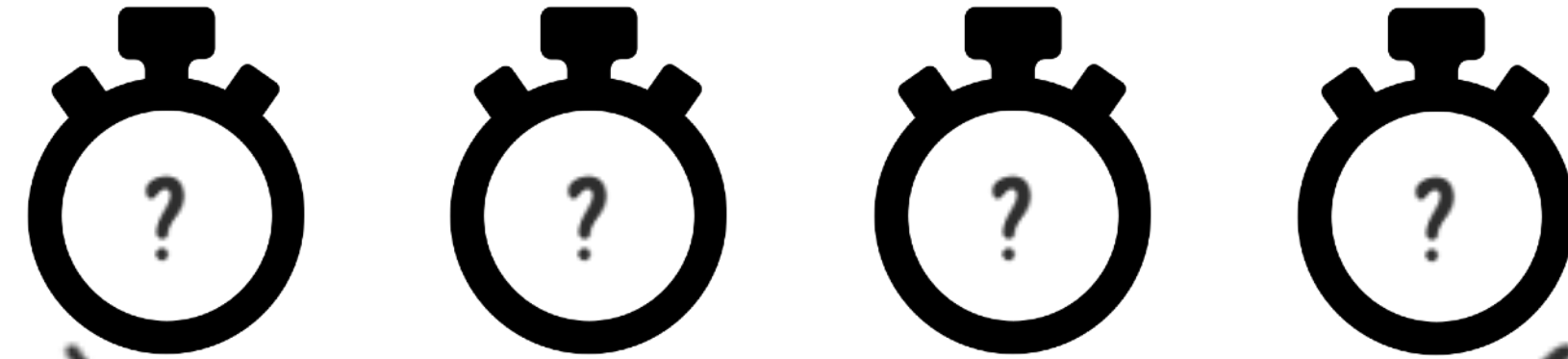
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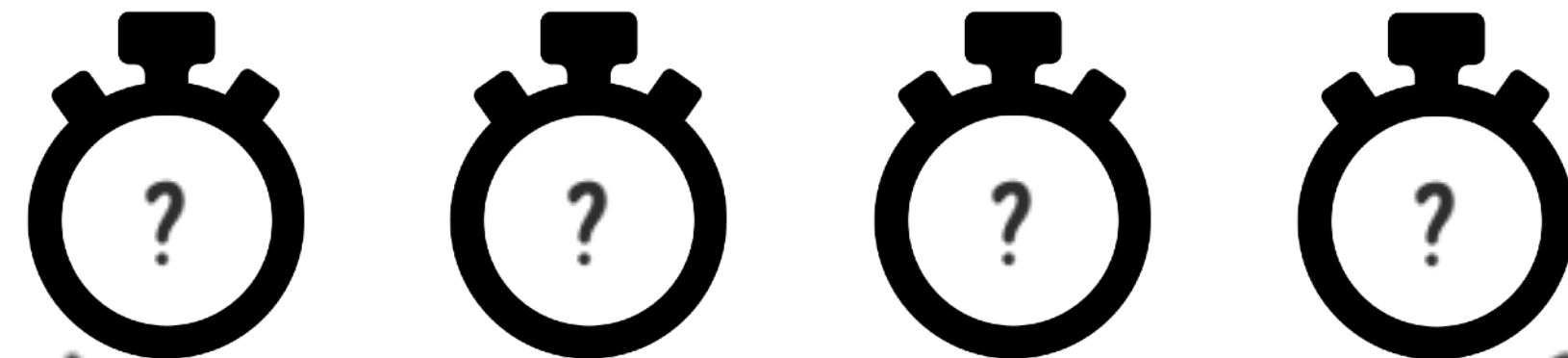
⋮



$\tilde{\mathbf{a}}^{(n)}$



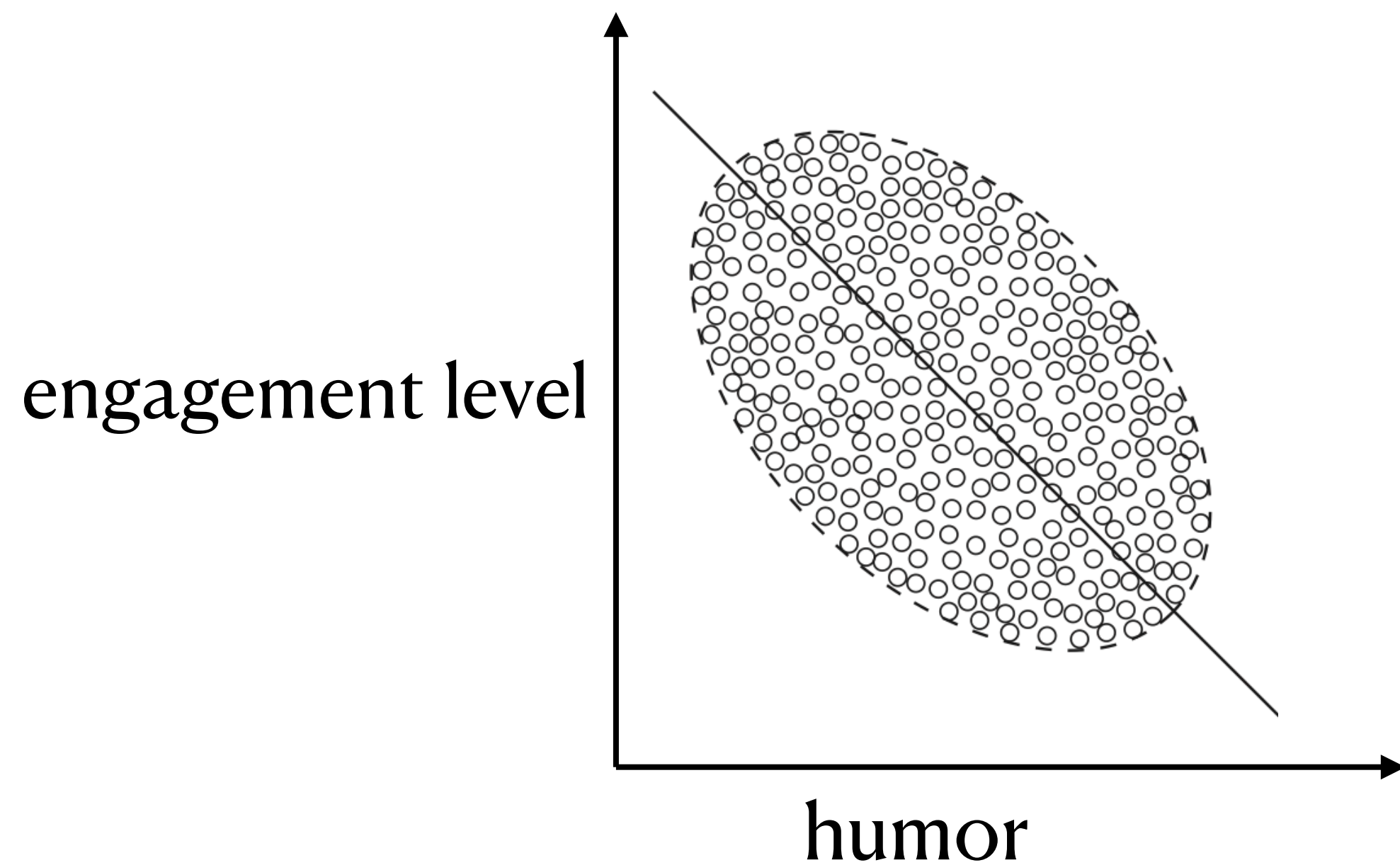
$\mathbf{y}^{(1)}(\tilde{\mathbf{a}}^{(1)}) ?$



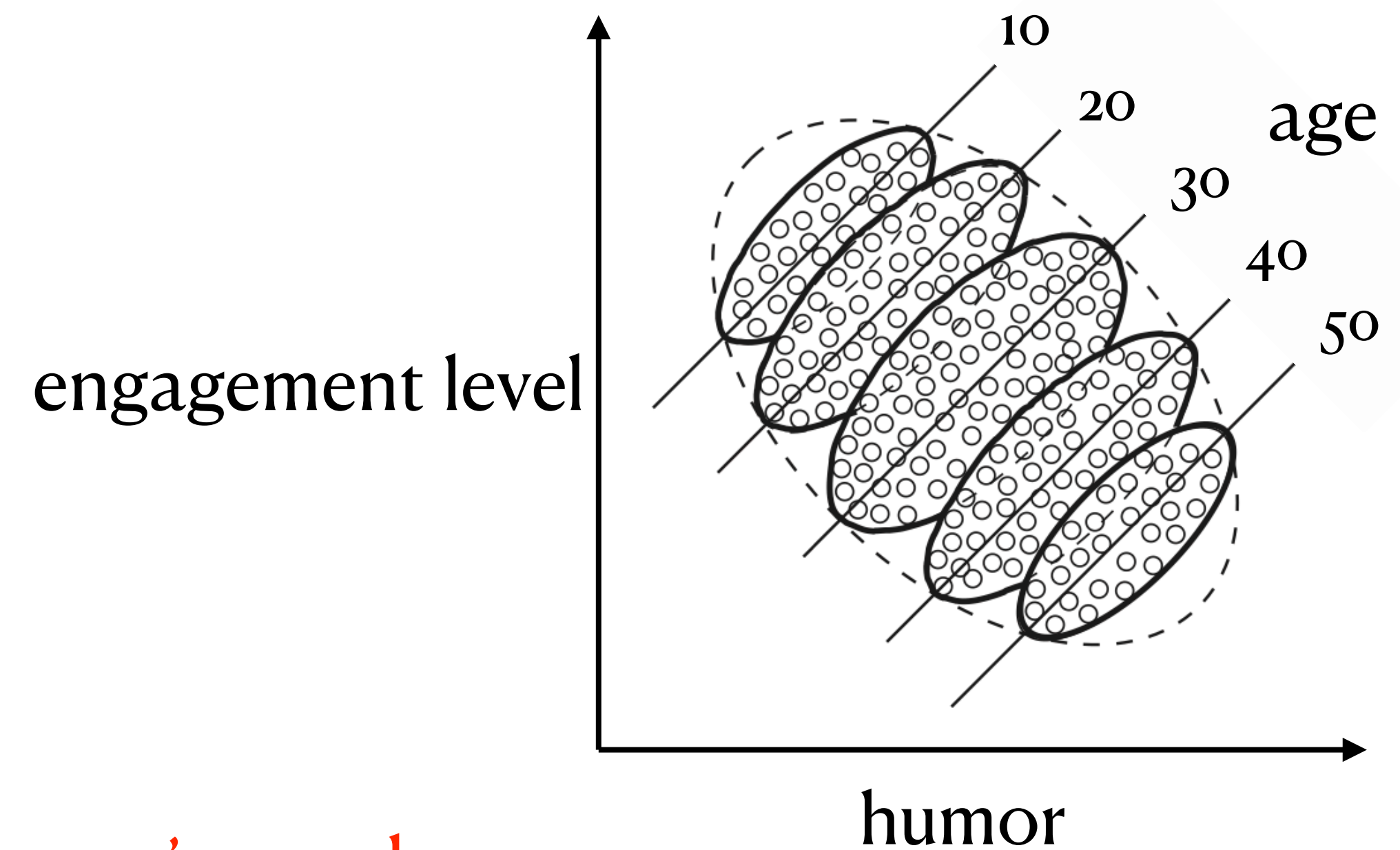
$\mathbf{y}^{(n)}(\tilde{\mathbf{a}}^{(n)}) ?$

Challenges

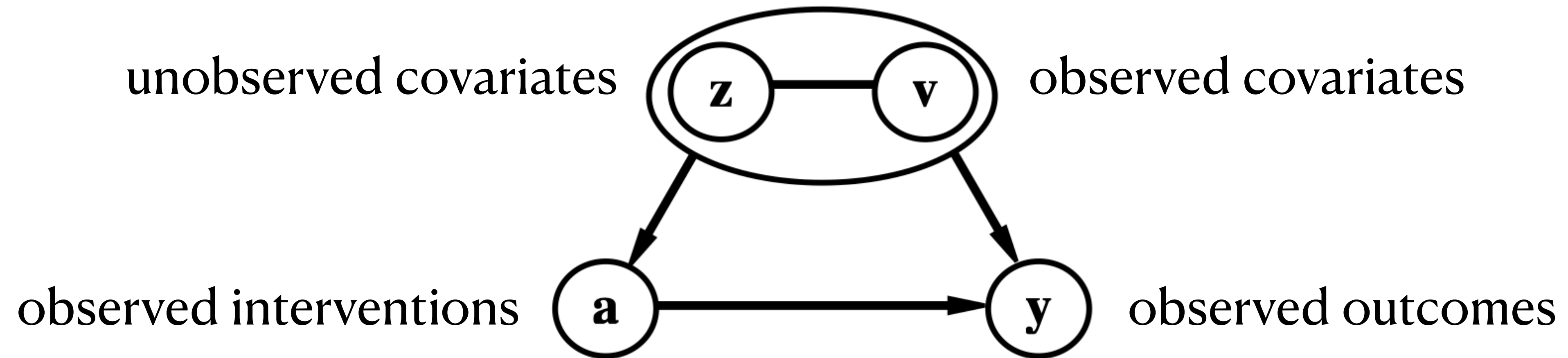
1. unobserved factors → **spurious associations**
2. users → **heterogeneous**
3. each user → a **single** interaction trajectory



Simpson's paradox



Problem Setup

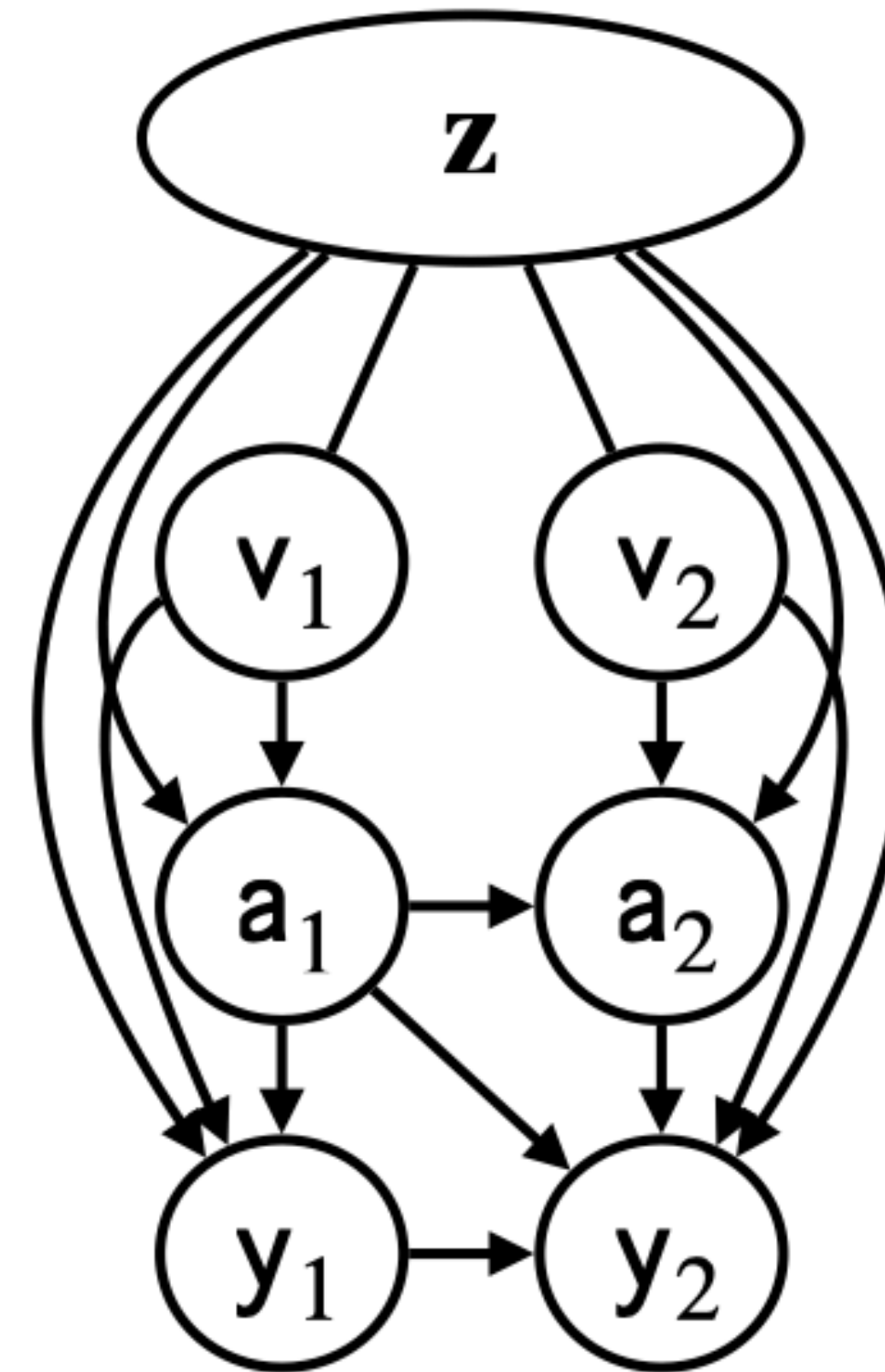
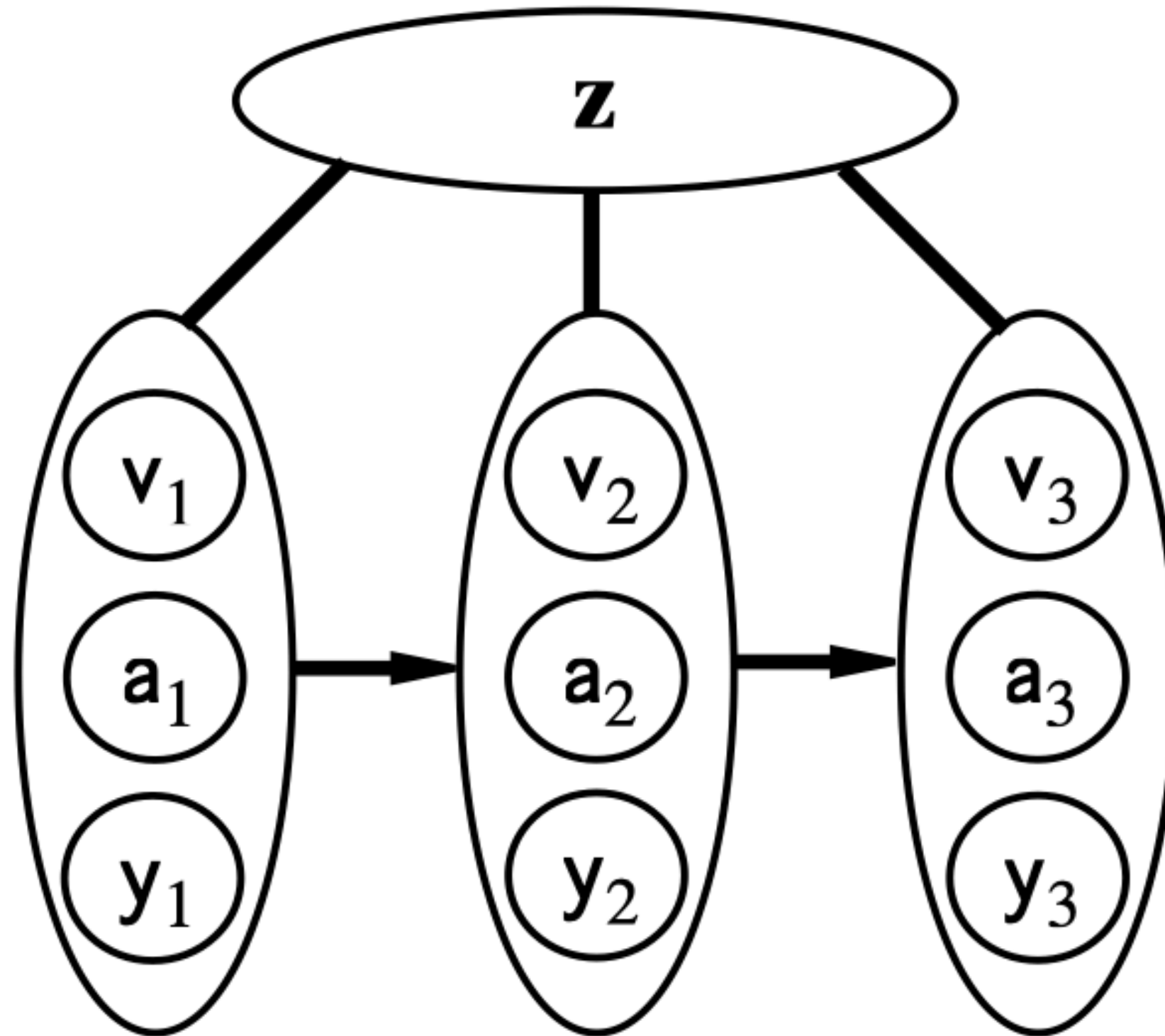
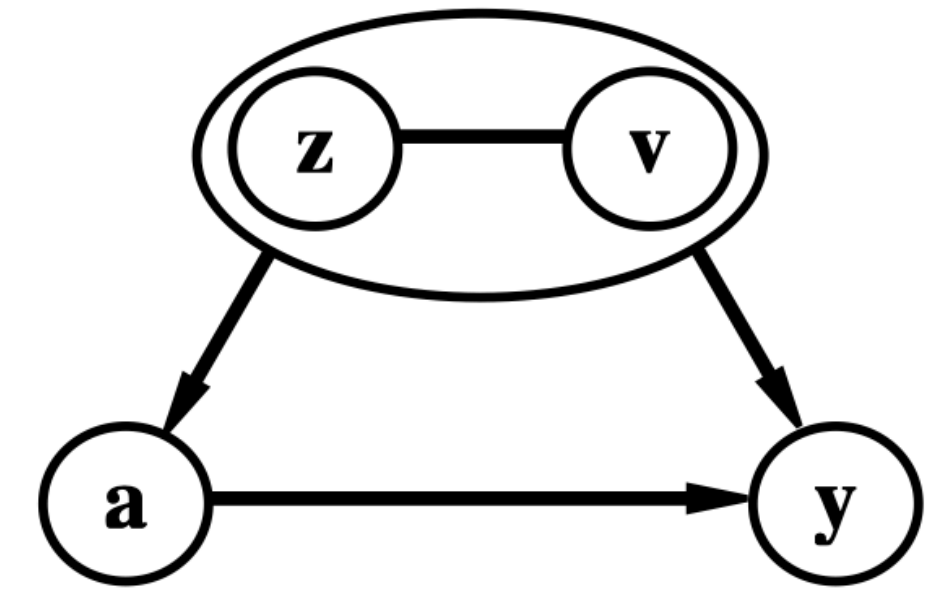


n heterogenous and independent users

one p -dimensional observation per user - $\{\mathbf{v}^{(i)}, \mathbf{a}^{(i)}, \mathbf{y}^{(i)}\}_{i=1}^n$

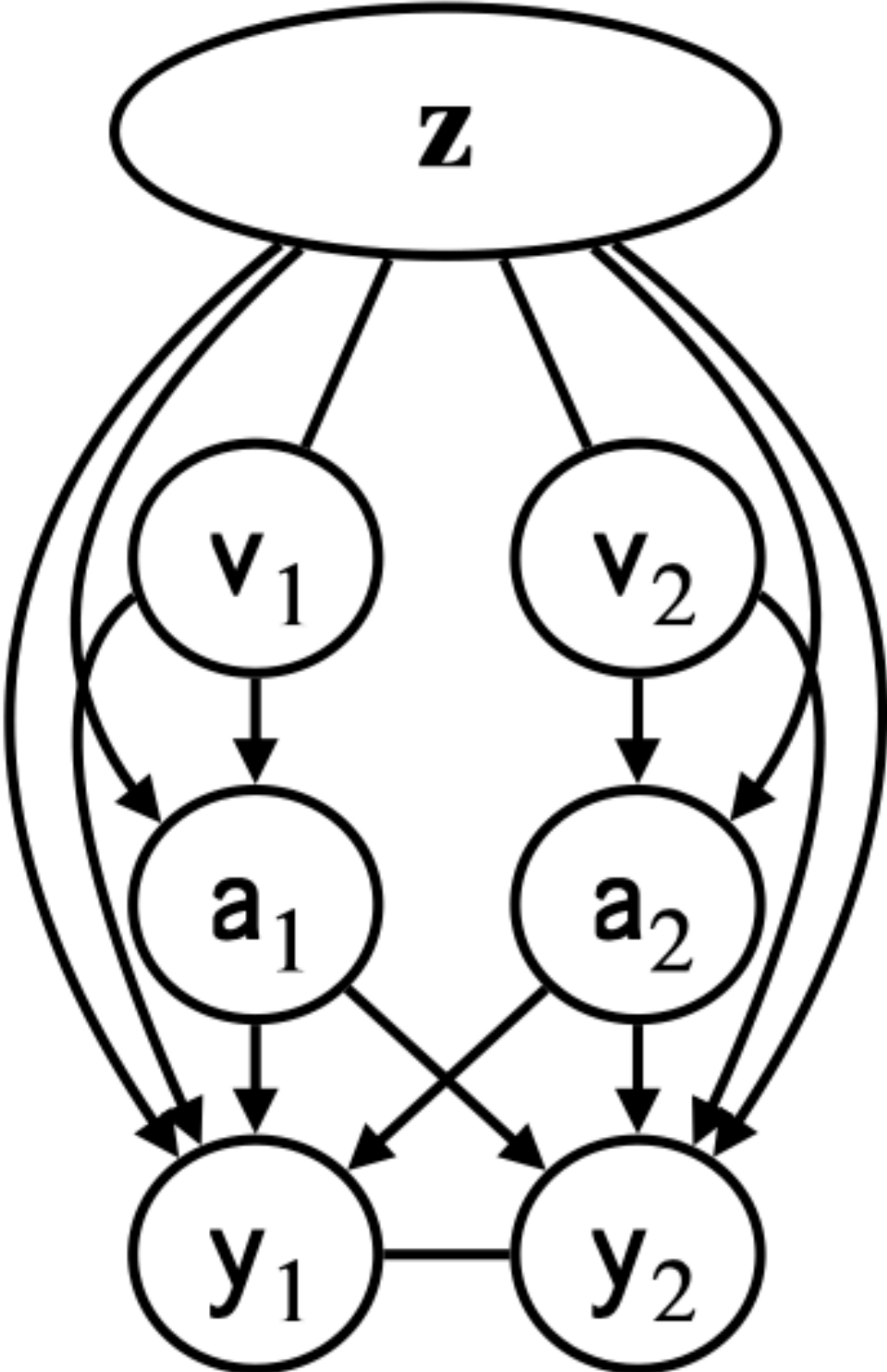
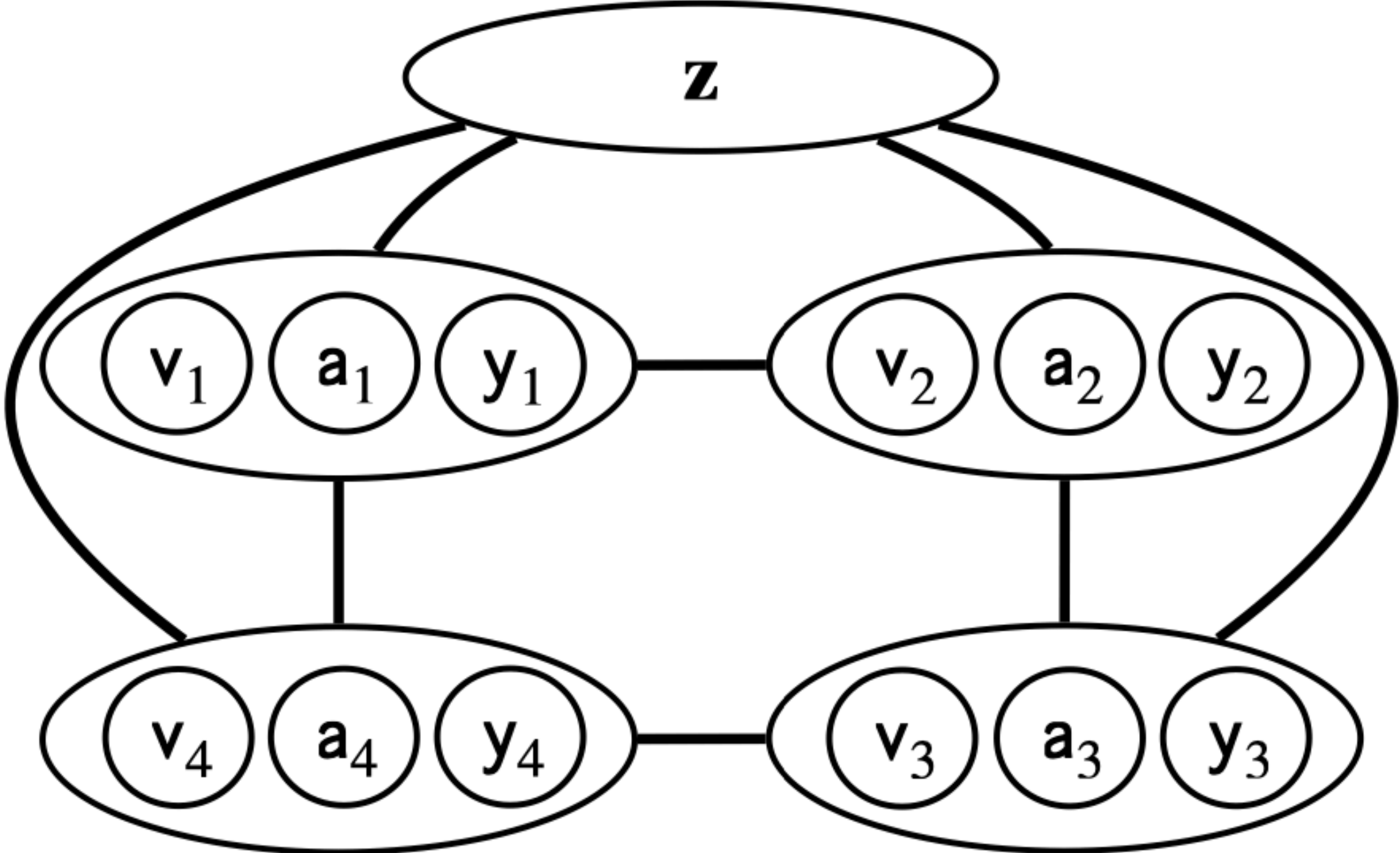
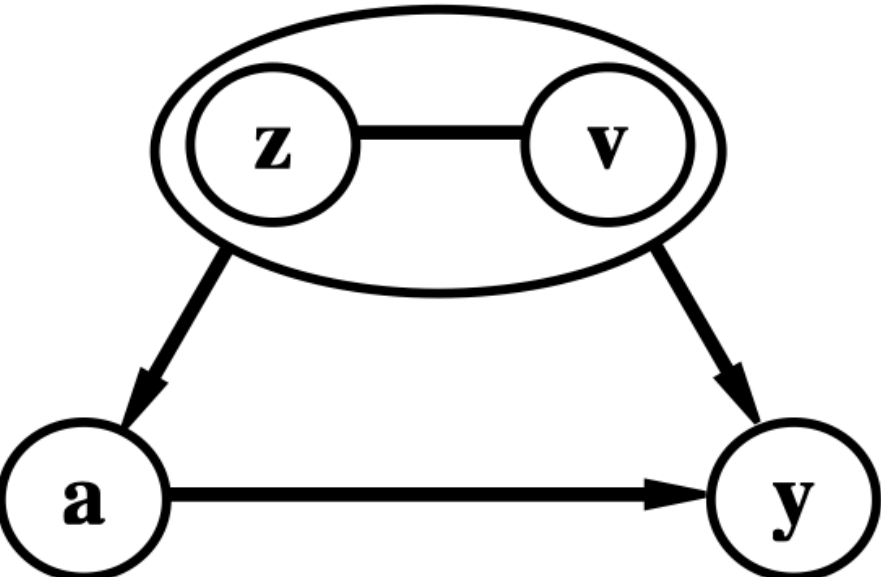
Examples

Sequential setting



Examples

Network setting



Goal: Counterfactual Questions

For user $i \in [n]$, what would have happened if **alternative treatments** were assigned?

≡

Estimate $\mathbf{y}^{(i)}(\tilde{\mathbf{a}}^{(i)})$ for $\tilde{\mathbf{a}}^{(i)} \in \mathcal{A}$?

suffices to learn $p(\mathbf{y} = \cdot \mid \mathbf{a} = \cdot, \mathbf{z}^{(i)}, \mathbf{v}^{(i)})$ for all $i \in [n]$

Heterogeneity: each user may have different *unobserved* \mathbf{z}

Can we learn n different distributions

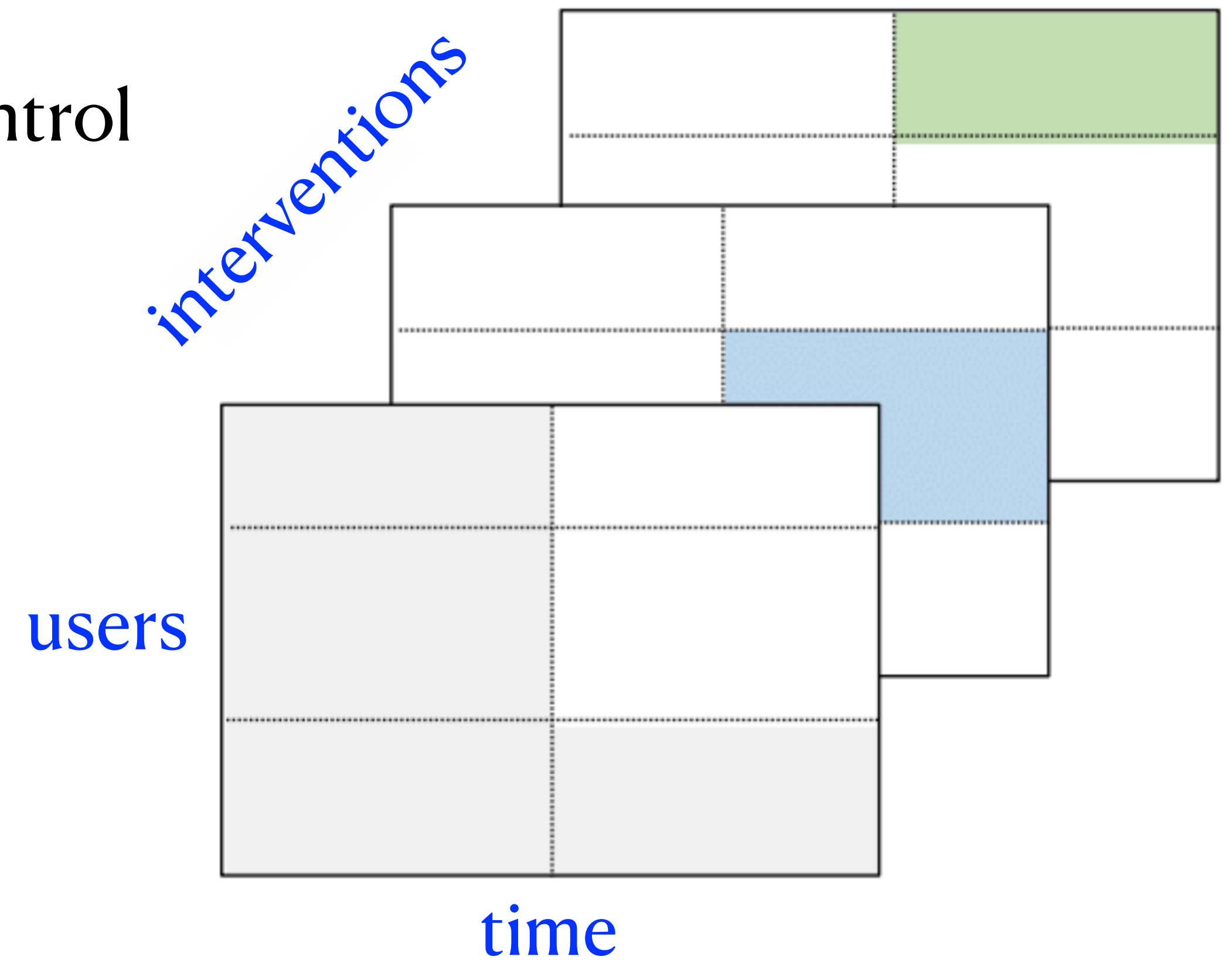
$p(\mathbf{y} = \cdot \mid \mathbf{a} = \cdot, \mathbf{z}^{(i)}, \mathbf{v}^{(i)}) \quad i \in [n]$

with *one* sample per distribution?

Related Work

Linear panel data

- Examples: difference in differences, synthetic control + variants, synthetic interventions + variants
- Only finitely many interventions
- Special structure on intervention assignment



Our Approach

Model the joint distribution of $\mathbf{w} \triangleq (\mathbf{z}, \mathbf{v}, \mathbf{a}, \mathbf{y})$ as a particular **exponential family**

$$p_{\phi, \Phi}(\mathbf{w}) \propto \exp\left(\phi^\top \mathbf{w} + \mathbf{w}^\top \Phi \mathbf{w}\right)$$

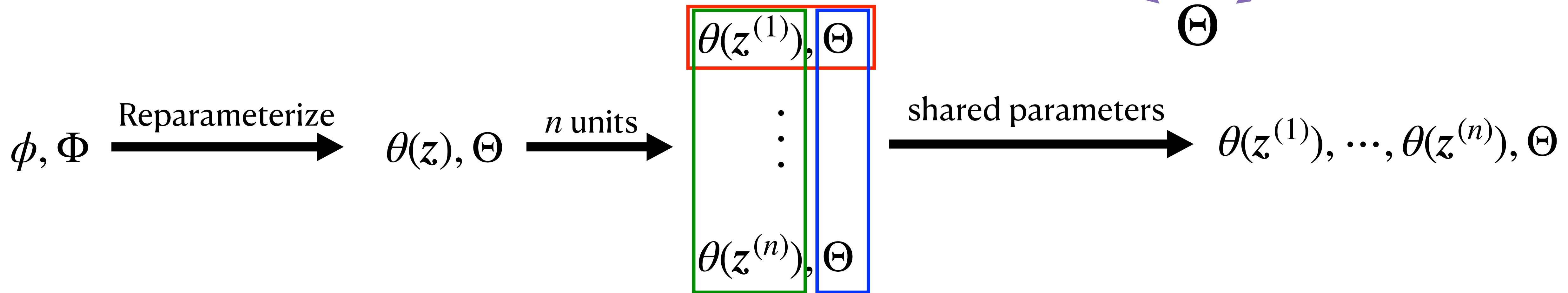


$$p(\mathbf{y} | \mathbf{a}, \mathbf{z} = \mathbf{z}^{(i)}, \mathbf{v} = \mathbf{v}^{(i)}) \propto \exp\left(\left[\phi_y^\top + \underbrace{2\mathbf{z}^{(i)\top} \Phi_{z,y} + 2\mathbf{v}^{(i)\top} \Phi_{v,y}}_{\text{different for different users}} + 2\mathbf{a}^\top \Phi_{a,y} \right] \mathbf{y} + \mathbf{y}^\top \Phi_{y,y} \mathbf{y}\right)$$

n heterogeneous conditional distributions \rightarrow **same exp. family** but with **diff. parameters**

Our Approach

$$p(\mathbf{y} | \mathbf{a}, \mathbf{z} = \mathbf{z}^{(i)}, \mathbf{v} = \mathbf{v}^{(i)}) \propto \exp \left(\left[\underbrace{\phi_y^\top + 2\mathbf{z}^{(i)\top} \Phi_{z,y} + 2\mathbf{v}^{(i)\top} \Phi_{v,y}}_{=\theta(\mathbf{z}^{(i)})} + 2\mathbf{a}^\top \Phi_{a,y} \right] \mathbf{y} + \mathbf{y}^\top \Phi_{y,y} \mathbf{y} \right)$$



1. If $\mathbf{z}^{(1)} = \dots = \mathbf{z}^{(n)} \rightarrow$ a single exponential family with n samples [B '15, KM '17, SSW '21, VML '22]
2. If $n = 1 \rightarrow$ a single exponential family with one sample (assume Θ is known) [KDDGD '21, MHBM' 21]

Inference Tasks

1. Parameters

- A. User-level — $\theta^*(\mathbf{z}^{(i)})$ for all $i \in [n]$

→ counterfactual
distribution

- B. Population-level — Θ^*

2. Expected potential outcomes — $\mathbf{E}[y^{(i)}(\tilde{\mathbf{a}}^{(i)}) \mid \mathbf{z} = \mathbf{z}^{(i)}, \mathbf{v} = \mathbf{v}^{(i)}]$

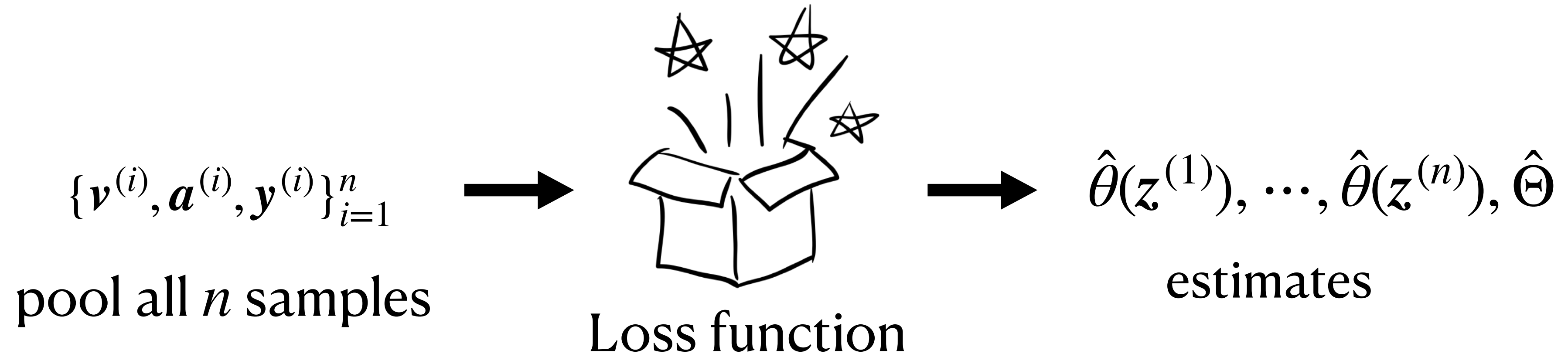
→ counterfactual
mean

Complexity of Parameter Space

Λ_θ — the set containing the true model parameters $\{\theta^\star(\mathbf{z}^{(i)})\}_{i \in [n]}$

	Linear combination of k -known vectors	s -sparse linear combination of k -known vectors
$M(\epsilon) = \log N(\Lambda_\theta, \epsilon)$	$O\left(k \cdot \log\left(1 + \frac{1}{\epsilon}\right)\right)$	$O\left(s \log k \cdot \log\left(1 + \frac{1}{\epsilon}\right)\right)$
$M_n(\epsilon) = nM(n\epsilon)$	$O\left(\frac{k}{\epsilon}\right)$	$O\left(\frac{s \log k}{\epsilon}\right)$

Parameter Estimation



$$\|\Theta^* - \hat{\Theta}\|_{2,\infty} \leq \epsilon$$

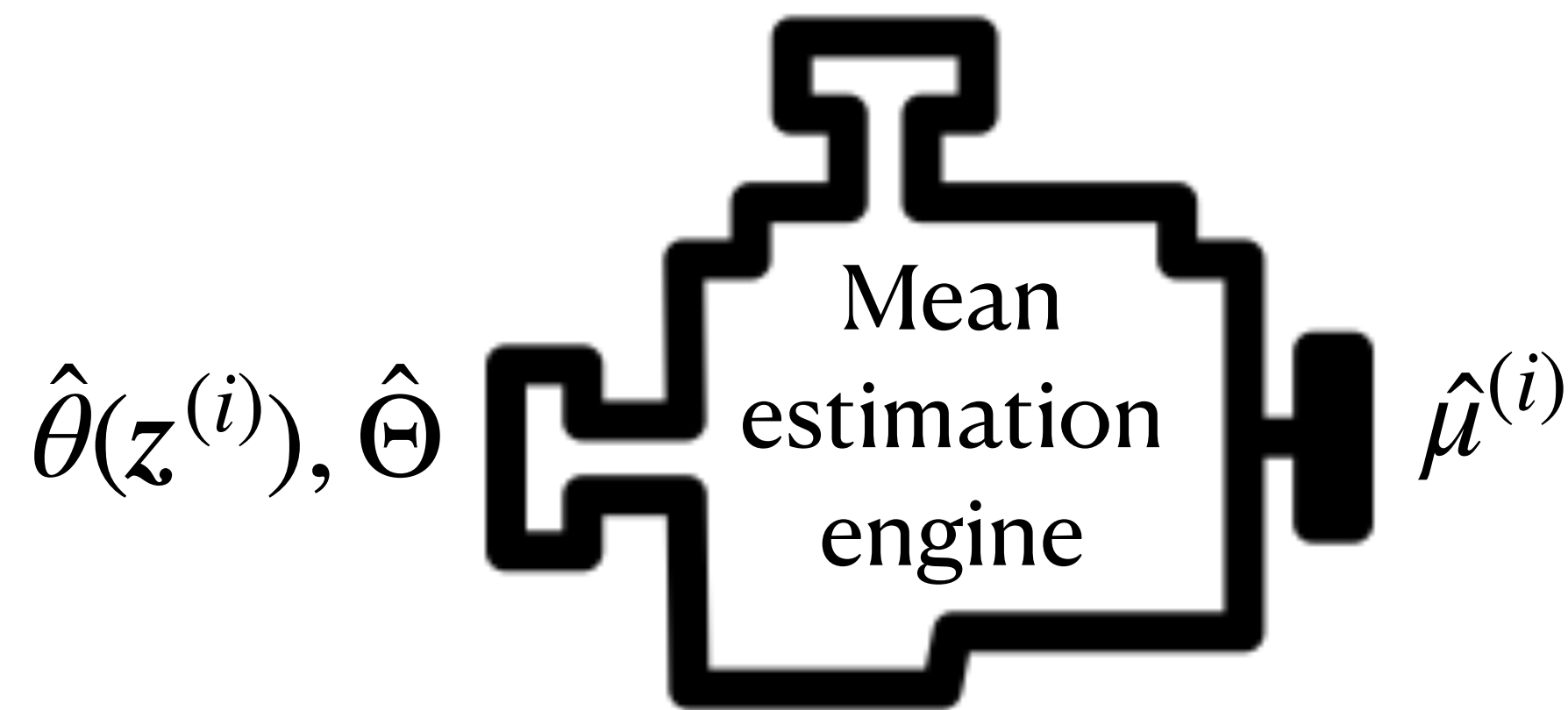
$$\text{when } n \geq O\left(\frac{p^2(p + M_n(\epsilon^2))}{\epsilon^4}\right)$$

$$\text{For all } i, \text{MSE}\left(\theta^*(\mathbf{z}^{(i)}), \hat{\theta}(\mathbf{z}^{(i)})\right) \leq \max\left\{\epsilon^2, \frac{M(c)}{p}\right\} \quad \text{when } n \geq O\left(\frac{p^2(pM(c) + M_n(\epsilon^2))}{\epsilon^4}\right)$$

Outcome Estimation

Expected potential outcomes — $\mu^{(i)} \triangleq \mathbf{E} \left[\mathbf{y}^{(i)}(\tilde{\mathbf{a}}^{(i)}) \mid \mathbf{z} = \mathbf{z}^{(i)}, \mathbf{v} = \mathbf{v}^{(i)} \right]$

$(\mathbf{v}^{(i)}, \tilde{\mathbf{a}}^{(i)})$



For all i , $MSE\left(\mu^{(i)}, \hat{\mu}^{(i)}\right) \leq \epsilon^2 + \frac{M(c)}{p}$ when $n \geq O\left(\frac{p^2(pM(c) + M_n(\epsilon^2))}{\epsilon^4}\right)$

$$\mathbf{x} \triangleq (\mathbf{v}, \mathbf{a}, \mathbf{y})$$

An Application

Denoise user-wise data

No systematically unobserved covariates \mathbf{z}

Noisy observed data = true data + measurement error

$$\bar{\mathbf{X}} \quad \mathbf{X} \quad \Delta \mathbf{x}$$

Assum 1: Only half users have error: $\Delta \mathbf{x}^{(i)} = \mathbf{0}$ for $i \in \{n/2, \dots, n\}$

Assum 2: Data has a sparse error: $\|\Delta \mathbf{x}^{(i)}\|_0 \leq s$ for $i \in \{1, \dots, n/2\}$

Goal: Estimate the true data

$$\text{For all } i, \|\mathbf{x}^{(i)}, \hat{\mathbf{x}}^{(i)}\|^2 \leq \max \left\{ \frac{\epsilon^2}{s}, \frac{s}{p} \right\} + \epsilon^2 \quad \text{when } n \geq O \left(\frac{s^2 p}{\epsilon^4} \right)$$

Remainder Of The Talk

The Loss Function, And Why It Works

Log likelihood as the loss function = Max. Likelihood Est.

not the right answer (computational challenge)

An alternative

a *proper* loss function, computationally efficient

ingredients of analysis

population-level parameter est through concentration due to many samples

user-level parameter est through *single* sample concentration due to

Log Sobolev + Dobrushin's criteria





Maximum Likelihood Estimation

Consider an exponential family $p_{\theta}(\mathbf{x}) = \frac{\exp(\theta^{\top} f(\mathbf{x}))}{Z(\theta)}$

Given independent $\mathbf{x}_1, \dots, \mathbf{x}_n \sim p_{\theta^*}(\mathbf{x})$, learn θ^* (or $\phi^{\top} \bar{\mathbf{w}} + \mathbf{w}^{\top} \Phi \mathbf{w}$)

$$\hat{\theta}_{MLE} \triangleq \operatorname{argmax}_{\theta} \operatorname{Log-Likelihood}(\theta)$$

$$\operatorname{Log-likelihood}(\theta) = \frac{1}{n} \sum_{i \in [n]} \theta^{\top} f(\mathbf{x}_i) - \log Z(\theta)$$

-  A. Consistency ?
-  B. Asymptotic normality ?
-  C. Asymptotic efficiency ?
-  D. Computational tractability ? **How to compute $Z(\theta)$?**

An Alternative

Consider an exponential family $p_{\theta}(\mathbf{x}) = \frac{\exp(\theta^{\top} f(\mathbf{x}))}{Z(\theta)}$

Given independent $\mathbf{x}_1, \dots, \mathbf{x}_n \sim p_{\theta^*}(\mathbf{x})$, learn θ^*

$$\hat{\theta} \triangleq \operatorname{argmin}_{\theta} \ell(\theta)$$

likelihood

$$\ell(\theta) = \frac{1}{n} \sum_{i \in [n]} \exp(-\theta^{\top} f(\mathbf{x}_i)) \quad \prod_{i \in [n]} \frac{1}{Z(\theta)} \exp(\theta^{\top} f(\mathbf{x}_i))$$

Convex constraint on θ \longrightarrow convex optimization problem

avoids $Z(\theta)$

but is it any good?

Properties

[SSW'21]

$$\hat{\theta} \in \arg \min_{\theta} \ell(\theta) = \frac{1}{n} \sum_{i \in [n]} \exp(-\theta^{\top} f(\mathbf{x}_i))$$

- ✓ A. Strictly proper loss function
- ✓ B. Consistency? $\hat{\theta}$ is MLE w.r.t. $p_{\theta^* - \theta}$ (not p_{θ})
- ✗ C. Asymptotic normality?
- ✓ D. Asymptotic efficiency?
- ✓ E. Computational tractability? No need to compute $Z(\theta)$!
- ✓ F. Finite sample guarantees?

Finite Sample Guarantees

[SSW'21]

$$\hat{\theta} \in \arg \min_{\theta} \ell(\theta) = \frac{1}{n} \sum_{i \in [n]} \exp(-\theta^\top f(\mathbf{x}_i))$$

$$\|\theta^* - \hat{\theta}\|_2 \sim n^{-1/4}$$

Proof ingredients —

- A. Concentration of gradient
- B. Anti-concentration of Hessian (Restricted strong convexity)

} Hoeffding's
inequality

Back To Our Setting

Condition on \mathbf{z}

Recall the joint distribution of $\mathbf{w} = (\mathbf{z}, \mathbf{v}, \mathbf{a}, \mathbf{y})$

$$p_{\phi, \Phi}(\mathbf{w}) \propto \exp\left(\phi^\top \mathbf{w} + \mathbf{w}^\top \Phi \mathbf{w}\right)$$

Letting $\mathbf{x} \triangleq (\mathbf{v}, \mathbf{a}, \mathbf{y})$, the conditional distribution of \mathbf{x} given \mathbf{z} can be written as

$$p_{\theta(\mathbf{z}), \Theta}(\mathbf{x} | \mathbf{z}) \propto \exp\left([\theta(\mathbf{z})]^\top \mathbf{x} + \mathbf{x}^\top \Theta \mathbf{x}\right)$$

$$p(\mathbf{y} | \mathbf{a}, \mathbf{z} = \mathbf{z}^{(i)}, \mathbf{v} = \mathbf{v}^{(i)}) \propto \exp\left(\left[\underbrace{\phi_y}_{\text{red}} + \underbrace{2\mathbf{z}^{(i)\top} \Phi_{z,y}}_{\text{red}} + \underbrace{2\mathbf{v}^{(i)\top} \Phi_{v,y}}_{\text{red}} + \underbrace{2\mathbf{a}^\top \Phi_{a,y}}_{\text{red}} \right] \mathbf{y} + \underbrace{\mathbf{y}^\top \Phi_{y,y} \mathbf{y}}_{\text{red}}\right)$$

$$p(x_t | \mathbf{x}_{-t}, \mathbf{z}) \propto \exp\left([\theta_t(\mathbf{z}) + 2\Theta_t^\top \mathbf{x}]x_t\right)$$

Structure On Parameters

$$p_{\theta(\mathbf{z}), \Theta}(\mathbf{x} | \mathbf{z}) \propto \exp\left([\theta(\mathbf{z})]^\top \mathbf{x} + \mathbf{x}^\top \Theta \mathbf{x}\right)$$

- (A) Every element of $\theta^\star(\mathbf{z}^{(1)}), \dots, \theta^\star(\mathbf{z}^{(n)})$, and Θ^\star are bounded
- (B) Every row of Θ^\star is sparse

$$\Lambda_\theta \triangleq \{\theta : \theta \text{ is consistent with (A) + low complexity}\}$$

$$\Lambda_\Theta \triangleq \{\Theta : \Theta \text{ is consistent with (A) and (B)}\}$$

required to
provide
meaningful
guarantees

$$p(x_t | \mathbf{x}_{-t}, \mathbf{z}) \propto \exp\left([\theta_t(\mathbf{z}) + 2\Theta_t^\top \mathbf{x}]x_t\right)$$

Learning Population-level Parameter

$$\mathcal{L}(\underline{\Theta}) = \sum_{t \in [p]} \frac{1}{n} \sum_{i \in [n]} \exp\left(-[\theta_t^{(i)} + 2\Theta_t^\top \mathbf{x}^{(i)}]x_t^{(i)}\right) \text{ where } \underline{\Theta} \triangleq [\theta^{(1)}, \dots, \theta^{(n)}, \Theta]$$

$\Lambda_{\Theta} \rightarrow$ (A) bounded elements, (B) sparse rows

Λ_{Θ} places independent constraints on the rows of Θ

p independent optimization problems

$$\mathcal{L}_t(\underline{\Theta}_t) = \frac{1}{n} \sum_{i \in [n]} \exp\left(-[\theta_t^{(i)} + 2\Theta_t^\top \mathbf{x}^{(i)}]x_t^{(i)}\right) \text{ for all } t \in [p] \longrightarrow \hat{\Theta}_t$$

$$\|\Theta_t^* - \hat{\Theta}_t\|_{2,\infty} \sim n^{-1/4}$$

A. Concentration of gradient

B. Anti-concentration of Hessian

} Hoeffding's
inequality

$$p(x_t | \mathbf{x}_{-t}, \mathbf{z}) \propto \exp\left([\theta_t(\mathbf{z}) + 2\Theta_t^\top \mathbf{x}]x_t\right)$$

Learning Unit-level Parameter

$$\mathcal{L}(\theta^{(1)}, \dots, \theta^{(n)}) = \sum_{t \in [p]} \frac{1}{n} \sum_{i \in [n]} \exp\left(-[\theta_t^{(i)} + 2\hat{\Theta}_t^\top \mathbf{x}^{(i)}]x_t^{(i)}\right)$$

$\Lambda_\theta \rightarrow$ (A) bounded elements, (B) low complexity

$\theta^{(1)}, \dots, \theta^{(n)} \in \Lambda_\theta^n$ places independent constraints on units, i.e., $\theta^{(i)} \in \Lambda_\theta$ for all $i \in [n]$

n independent optimization problems

$$\mathcal{L}^{(i)}(\theta^{(i)}) = \sum_{t \in [p]} \exp\left(-[\theta_t^{(i)} + 2\hat{\Theta}_t^\top \mathbf{x}^{(i)}]x_t^{(i)}\right) \text{ for all } i \in [n] \quad \longrightarrow \quad \hat{\theta}^{(i)}$$

$$\|\theta^*(\mathbf{z}^{(i)}) - \hat{\theta}^{(i)}\|_2 \sim \max\{n^{-1/4}, M\}$$

A. Concentration of gradient

B. Anti-concentration of Hessian

} Logarithmic
Sobolev
inequality