

Front-door Adjustment Beyond Markov Equivalence with Limited Graph Knowledge





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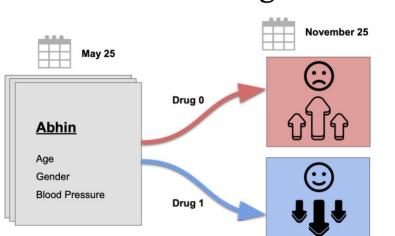


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Causal Effect Estimation

Causal effect of a drug on cholesterol level from observational data



 $\mathbb{P}(\text{cholesterol} | do(\text{drug}))$?

Observational Data

Age	Gender	Blood Pressure	Drug	Cholesterol (0)	Cholesterol (1)
22	Male	145/95	0	î	?
26	Female	135/80	0	11	?
58	Female	130/70	1	?	ŶÎŶ
24	Female	150/85	1	?	tît

Observed features x

Treatment t

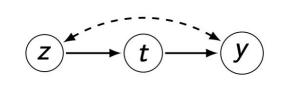
Outcome y

Causal Estimands With Known Graph

Given the complete knowledge of the causal graph, a complete algorithm was proposed for causal effect estimation [1,2]

Special Case 1 — Back-door Criterion

A set **z** satisfies the back-door criterion if

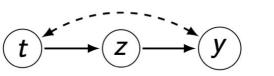


- all paths between t and y containing an arrow into t (i.e., back-door paths) are blocked by z
- 2. \mathbf{z} does not contain any descendant of t

$$\mathbb{P}(y \mid do(t=t)) = \sum_{\mathbf{z}} \mathbb{P}(y \mid t=t, \mathbf{z}=z) \mathbb{P}(\mathbf{z}=z)$$

Special Case 2 — Front-door Criterion

A set z satisfies the front-door criterion if



- **z** blocks all directed paths from *t* to *y*
- all back-door paths between t and z are blocked
- all back-door paths between z and y are blocked by t

$$\mathbb{P}(y \mid do(t=t)) = \sum_{\mathbf{z}} \left(\sum_{t'} \mathbb{P}(y \mid t=t', \mathbf{z}=z) \mathbb{P}(t=t') \right) \mathbb{P}(\mathbf{z}=z \mid t=t)$$

Causal Estimands Without Graph

Given partial ancestral graphs (PAGs), which can be learned from observational data, complete algorithms were proposed for causal effect estimation [3,4]

PAGs — A collection of causal graphs that encode the same conditional independence relations

Drawbacks —

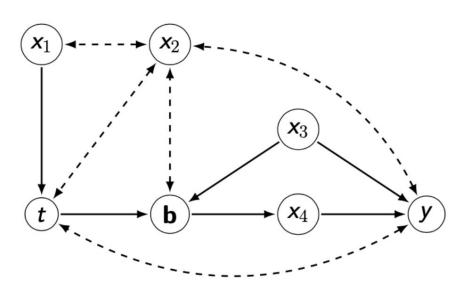
- A. Only applicable if every causal graph in the collection has the same causal estimand
- B. Sequentiality in learning PAGs propagates errors between tests.
- C. PAG learning cannot incorporate side information about the graph.

Causal Estimands With Limited Graph Knowledge?

How much of the causal graph \mathcal{G} do we need to know?

[5,6,7,8] — How to identify back-door-like sets using only partial structural information?

This work — How to identify front-door-like sets using only partial structural information?



The knowledge of all the children of the treatment is sufficient!

 \rightarrow (**b**) in the above graph

- Semi-Markovian Model Assumptions —

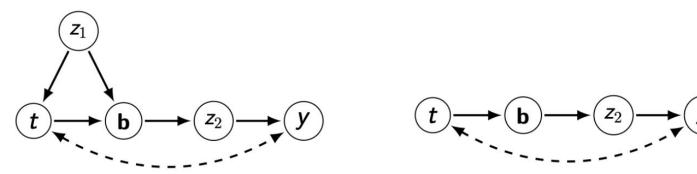
- 1. y is a descendant of t.
- There is an unobserved confounder (denoted by a bi-directed arrow) between *y* and *t*.

Sufficient Conditions For Causal Identifiability

- **b**: the set of all children of t.
- Consider any subset of the remaining observed features i.e., $\mathbf{z} \subseteq \mathbf{x} \setminus \{\mathbf{b}\}$.
- $\exists z$ such that $\mathbf{b} \perp y \mid t, \mathbf{z} \implies \mathbb{P}(y \mid do(t=t))$ is identifiable from observational data

e.g.,
$$\mathbf{z} = (\mathbf{x}_3, \mathbf{x}_4)$$
 in \mathcal{G}_{tov}

Proof Idea — Show that there is no bi-directed path between t and **b** in $\mathcal{G}^{\text{Ancestor}(y)}$ + [9] However, $\mathbf{b} \perp y \mid t$, \mathbf{z} alone is insufficient to establish a unique causal formula.



These graphs satisfy $\mathbf{b} \perp y \mid t, \mathbf{z}$ but have different causal formula.

Generalized Front-door Criterion

- Two additional conditional independencies imply a unique causal formula!
- If **z** satisfying $\mathbf{b} \perp y \mid t$, **z** can be decomposed into $\mathbf{z}^{(o)} \subseteq \mathbf{z}$ and $\mathbf{z}^{(i)} = \mathbf{z} \setminus \mathbf{z}^{(o)}$ such that

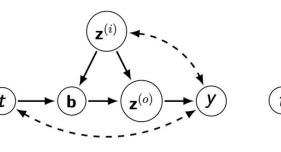
$$\mathbf{z}^{(i)} \perp t$$
 and $\mathbf{z}^{(o)} \perp t \mid \mathbf{z}^{(i)}, \mathbf{b}$

then. \mathbf{z} and $\mathbf{s} \triangleq (\mathbf{b}, \mathbf{z}^{(i)})$ are generalized front-door sets, i.e.,

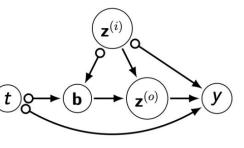
$$\mathbb{P}(y|do(t=t)) = \sum_{\mathbf{z}} \left(\sum_{t'} \mathbb{P}(y|t=t',\mathbf{z}=z) \mathbb{P}(t=t') \right) \mathbb{P}(\mathbf{z}=z|t=t)$$

$$\mathbb{P}(y|do(t=t)) = \sum_{\mathbf{s}} \left(\sum_{t'} \mathbb{P}(y|t=t',\mathbf{s}=s) \mathbb{P}(t=t') \right) \mathbb{P}(\mathbf{s}=s|t=t)$$
e.g., $\mathbf{z}^{(i)} = \mathbf{x}_3$ and $\mathbf{z}^{(o)} = \mathbf{x}_4$ in \mathcal{G}_{tov}

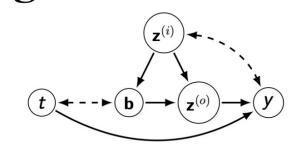
Relation To PAG-based Algorithms



Graph \mathcal{G}_1 where our method applies



PAG corresponding to graphs \mathcal{G}_1 and \mathcal{G}_2



Graph \mathcal{G}_2 which is Markov equivalent to \mathcal{G}_1

IDP algorithm fails here!

Algorithm For ATE Estimation

```
ATE_z^r = 0, ATE_s^r = 0, c_2 = 0;
          \mathbf{if} \ CI(\mathbf{b} \perp_p \mathbf{y} | \mathbf{z}, t) > p_v \ \mathbf{then} // where CI stands for conditional independence
                     if \min\{CI(\mathbf{z}^{(i)} \perp_p t), CI(\mathbf{z}^{(o)} \perp_p t | \mathbf{b}, \mathbf{z}^{(i)})\} > p_v) then
                           \text{ATE}_z^{\text{r}} = \text{ATE}_z^{\text{r}} + \frac{\sum_{j:t_j=1}^{r} \sum_{t'} \mathbb{E}[y|\mathbf{z}_j,t']\mathbb{P}(t')}{\mathbb{E}[y|\mathbf{z}_j,t']\mathbb{P}(t')} - \frac{\sum_{j:t_j=0} \sum_{t'} \mathbb{E}[y|\mathbf{z}_j,t']\mathbb{P}(t')}{\mathbb{E}[y|\mathbf{z}_j,t']\mathbb{P}(t')}
     ATE_z = ATE_z/c_1, ATE_s = ATE_s/c_1;
Failed to find \mathbf{z} = (\mathbf{z}^{(i)}, \mathbf{z}^{(o)}) satisfying (4) and (5);
```

Applicability To Random Graphs

• p-#observed variables • d- expected in-degree • q- controls #unobserved variables

Let $y = v_p$; t =any non-parent and non-grand parent ancestor of y; b =all children of t

	p = 10			p = 15		
	d = 2	d = 3	d = 4	d = 2	d = 3	d =
q = 0.0	(43, 43)	(20, 20)	(21, 21)	(27, 26)	(9,9)	(4,
q = 0.5	(23, 23)	(16, 16)	(7,7)	(18, 17)	(4, 3)	(0,
q = 1.0	(6,6)	(4,4)	(5,5)	(9,9)	(10, 9)	(0,

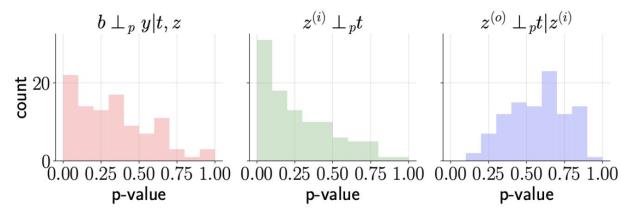
IDP gives 0 success out of 100 across for various p, d, and q

Fairness Application — German Credit Dataset

Compute the total effect of the sensitive attribute t on the outcome y

 $y = \text{binary credit risk}; \quad t = \text{applicant's age (binarized)};$

b = # of people financially dependent on the applicant, applicant's savings, applicant's job



Total effect_z = 0.0125 ± 0.0011 , and Total effect_s = 0.0105 ± 0.0018

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